

Euclidean Distance Matrices & SDP

$D \in S^n$ is an EDM if $\exists p_1, \dots, p_n \in \mathbb{R}^d$
s.t.,
 $D_{ij} = \|p_i - p_j\|^2, \quad \forall i, j = 1, \dots, n.$

The smallest such d is called the embedding dimension of D , denoted $\text{embdim}(D)$.

Let $Y \in S^n$ s.t. $Y_{ij} = p_i^T p_j, \quad \forall i, j.$ (Gram matrix)

$$\begin{aligned}\text{Then } D_{ij} &= \|p_i - p_j\|^2 \\ &= p_i^T p_i + p_j^T p_j - 2 p_i^T p_j \\ &= Y_{ii} + Y_{jj} - 2 Y_{ij} =: \mathcal{K}(Y)_{ij}.\end{aligned}$$

$\therefore \mathcal{K} : S^n \rightarrow S^n$ is linear and satisfies

$$\mathcal{K}(S_+^n) = \mathcal{E}^n,$$

$\begin{matrix} \text{p.s.d.} & \text{EDM} \\ \text{cone} & \text{cone} \end{matrix}$

but not one-to-one, since translating the points gives the same EDM, but a different Gram matrix.

$\therefore$ we centre the points at the origin:

$$\sum_{i=1}^n p_i = 0 \quad (\text{equivalently, } Y_e = 0).$$

Then

$$\mathcal{K}(S_+^n \cap S_c^n) = \mathcal{E}^n \quad \text{and} \quad \mathcal{K}^+(\mathcal{E}^n) = S_+^n \cap S_c^n,$$

where $S_c^n := \{Y \in S^n : Y_e = 0\}.$

Moreover,

$$\text{embdim}(D) = \text{rank}(K^+(D)), \quad \forall D \in \mathcal{E}^n,$$

EDM completion

Suppose D_{ij} only known for $ij \in E$.

The minimum rank EDM completion problem is:

$$\begin{aligned} \min \text{embdim}(D) \\ \text{s.t. } D_{ij} = D_{ij}, \forall ij \in E \\ D \in \mathcal{E}^n \end{aligned} \quad \equiv \quad \begin{aligned} \min \text{rank}(Y) \\ \text{s.t. } K(Y)_{ij} = D_{ij}, \forall ij \in E \\ Y \in S_+^n \cap S_c^n. \end{aligned}$$

Applications

① Molecular conformation from NMR

$$\left[\begin{array}{l} \text{find } Y \in S_+^n \cap S_c^n \\ \text{s.t. } K(Y)_{ij} = D_{ij}, \forall ij \in E \\ \text{rank}(Y) = 3 \end{array} \right]$$

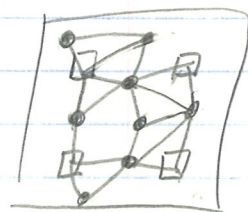
$$\left[\begin{array}{l} \text{find } p_1, \dots, p_n \in \mathbb{R}^3 \\ \text{s.t. } \|p_i - p_j\|^2 = D_{ij}, \forall ij \in E \end{array} \right]$$

Determine the atom positions from the partial distance information

② Sensor network localization

$$\left[\begin{array}{l} \text{find } X \in \mathbb{R}^{n \times 2} \\ \text{s.t. } K([X][X]^T)_{ij} = D_{ij}, \forall ij \in E \end{array} \right]$$

$$\left[\begin{array}{l} \text{find } x_1, \dots, x_n \in \mathbb{R}^2 \\ \text{s.t. } \|x_i - x_j\|^2 = D_{ij}, \forall ij \in E_x \\ \|x_i - a_j\|^2 = D_{ij}, \forall ij \in E_a \end{array} \right]$$



$$\left[\begin{array}{l} \text{find } Y \in S_+^{nm} \\ \text{s.t. } K(Y)_{ij} = D_{ij}, \forall ij \in E \\ Y_{aa} = AA^T \\ \text{rank}(Y) = 2 \end{array} \right]$$

$a_1, \dots, a_m \in \mathbb{R}^2$ are anchors (positions known)

- ③ Nonlinear dimensionality reduction
 a.k.a. nonlinear PCA
 a.k.a. manifold unfolding



$$x_1, \dots, x_n \in \mathbb{R}^D$$

$$p_1, \dots, p_n \in \mathbb{R}^d$$

Maximum Variance Unfolding (MVU):

$$\left[\begin{array}{l} \max \quad \text{trace}(Y) \\ \text{s.t.} \quad X(Y)_{ij} = D_{ij}, \forall ij \in E \\ Y \in S_+^n \cap S_c^n \end{array} \right]$$

Note: $Y_{ij} = p_i^T p_j \Rightarrow \text{trace}(Y) = \sum_{i=1}^n \|p_i\|^2$

Semidefinite Facial Reduction

Let $F := \{Y \in S_+^n \cap S_c^n : X(Y)_{ij} = D_{ij}, \forall ij \in E\}$.

If $F \subseteq U S_+^k U^T \leftarrow$ a face of S_+^n
 then we get a smaller equivalent problem
 using the substitution

$$Y = U Z U^T, \quad Z \in S_+^k.$$

Noisy distances

$$\forall ij \in E$$

If $d_{ij} = \|p_i - p_j\| (1 + \sigma \epsilon_{ij})$ [Mult. noise model]

where ϵ_{ij} is random with normal distribution (mean = 0, std. dev. = 1)

Then the maximum likelihood positions are the opt. sol'n of the nonlinear least-squares problem:

$$\begin{aligned} \min \quad & \sum_{ij \in E} v_{ij}^2 \\ \text{s.t.} \quad & \|p_i - p_j\|^2 (1 + v_{ij})^2 = d_{ij}^2, \forall ij \in E \\ & \sum_{i=1}^n p_i = 0 \\ & p_1, \dots, p_n \in \mathbb{R}^d \end{aligned}$$